



**NOAA
FISHERIES**

Innovative Camera Applications for Electronic Monitoring

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Overview

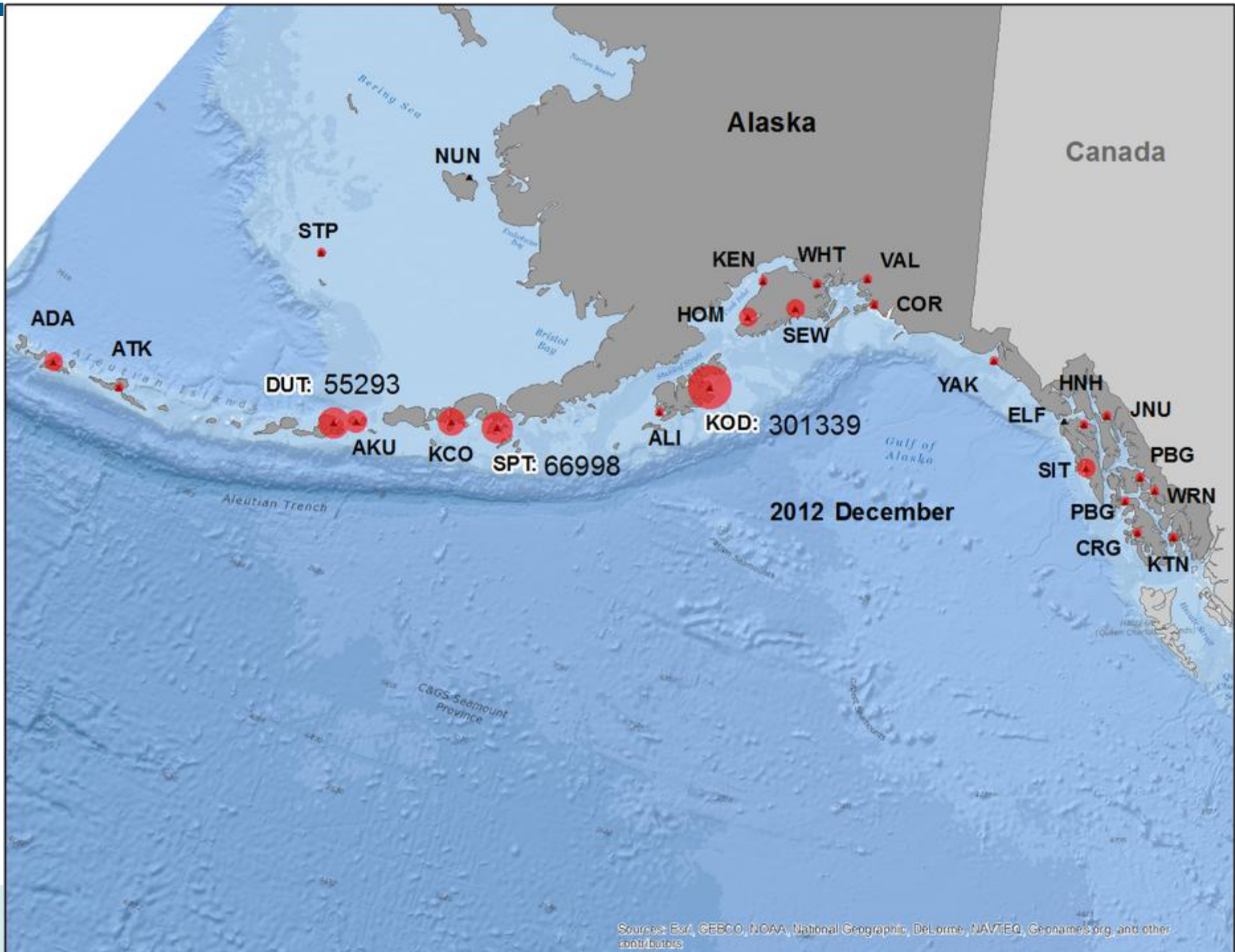
- Background
- Goals
- Beta version
- Image processing
- Future Work

The North Pacific Fisheries Management Council's October 2012 Motion

“The Council requests that NMFS provide a strategic planning document for electronic monitoring (EM) that identifies the Council’s EM management **objective of collecting at-sea discard estimates from the 40’ – 57.5’ IFQ fleet**”

IFQ Fleet





Sources: Esri, GEBCO, NOAA, National Geographic, DeLorme, NAVTEQ, Geonames.org, and other contributors

What are the requirements to use EM for conducting at-sea sampling for bycatch estimation?

- Bycatch Estimation
 - Ability to estimate weight
 - Ability to provide disposition of catch
 - Ability to estimate effort
 - Representative sample
- Uninterrupted data stream of consistent high quality data and infrastructure to support it
- Must be timely
- Must be cost effective



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Current uses of Camera based EM

- Has been shown to be an effective tool to satisfy a variety of monitoring objectives in compliance based programs.
 - British Columbia, Canada (logbook audit)
 - Alaska (bin monitoring and flow scale)
- EM data are not used in bycatch estimation

Goals

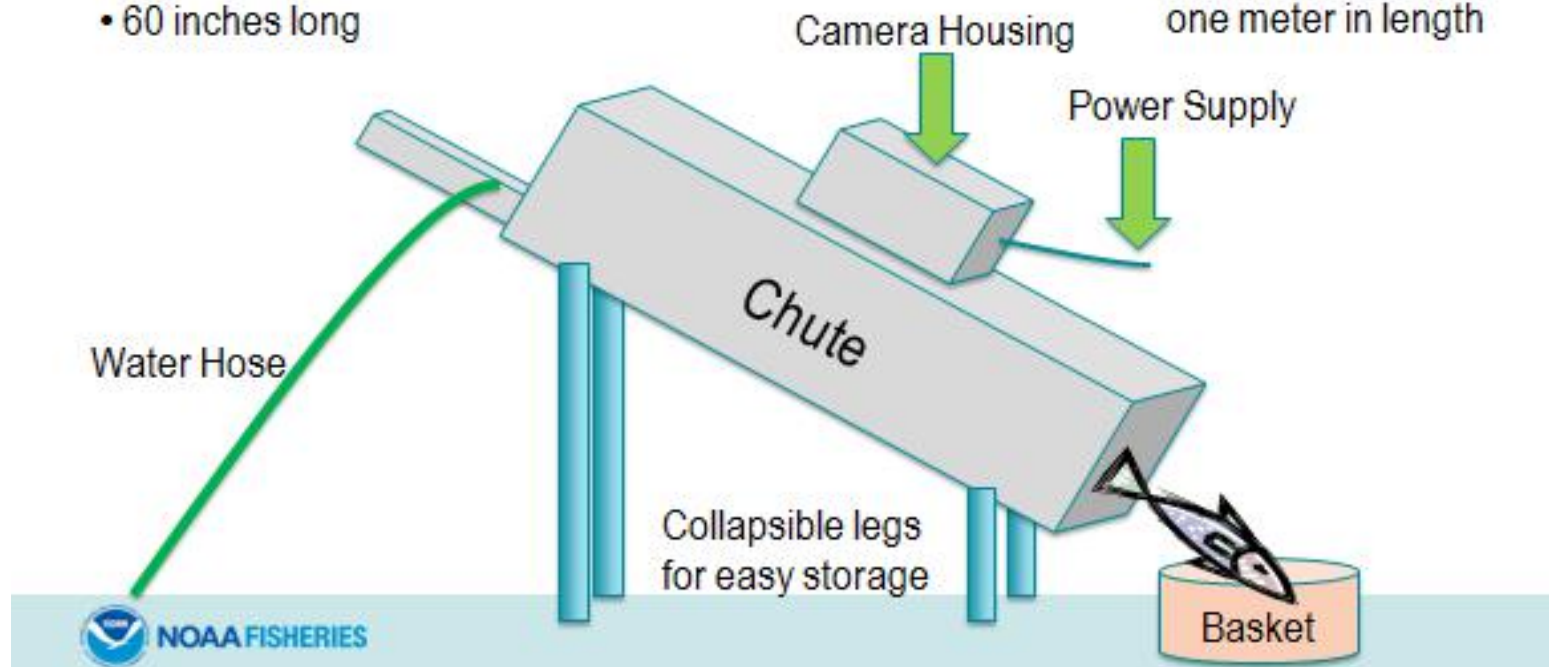
- Improve data quality
 - Collect high quality images consistently
- Support catch accounting system
 - Data integration into observer database
- Automate length acquisition and species ID
 - Decrease time between data collection and use
 - Improve cost benefit by minimizing post processing and storage
 - Infer weight from length for estimation

Beta test version

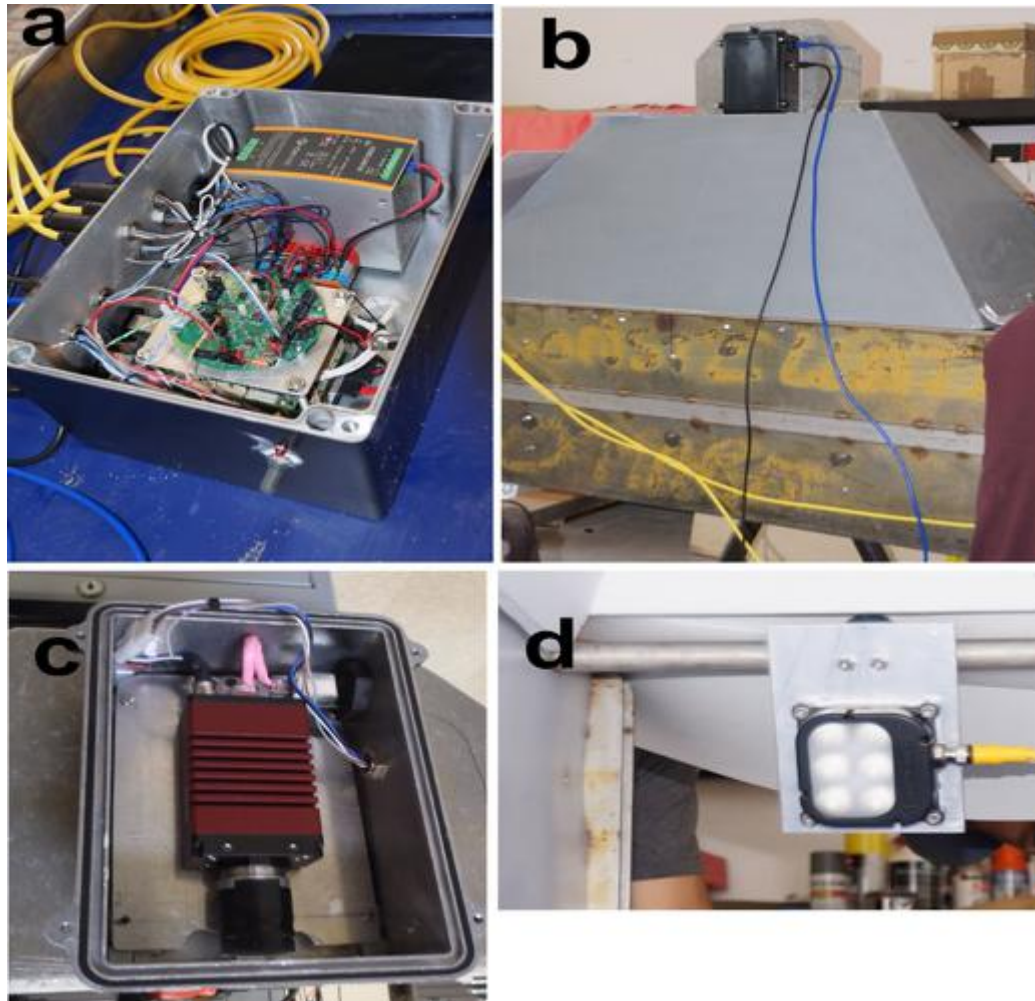
Camera Chute

- Chute Dimensions
 - 30 inches wide
 - 18 inches tall
 - 60 inches long

- Aluminum construction
- Mobile
- Light shield both ends
- Two internal Strobes
- Photographs fish up to one meter in length



Concept



Camera-Chute Length Measurement

- Self-contained software
 - Process images from camera-chute system
- Specifications
 - Camera calibration
 - Taking background images to adjust the lighting
 - Output the fish box coordinates and real-unit length



Image Processing

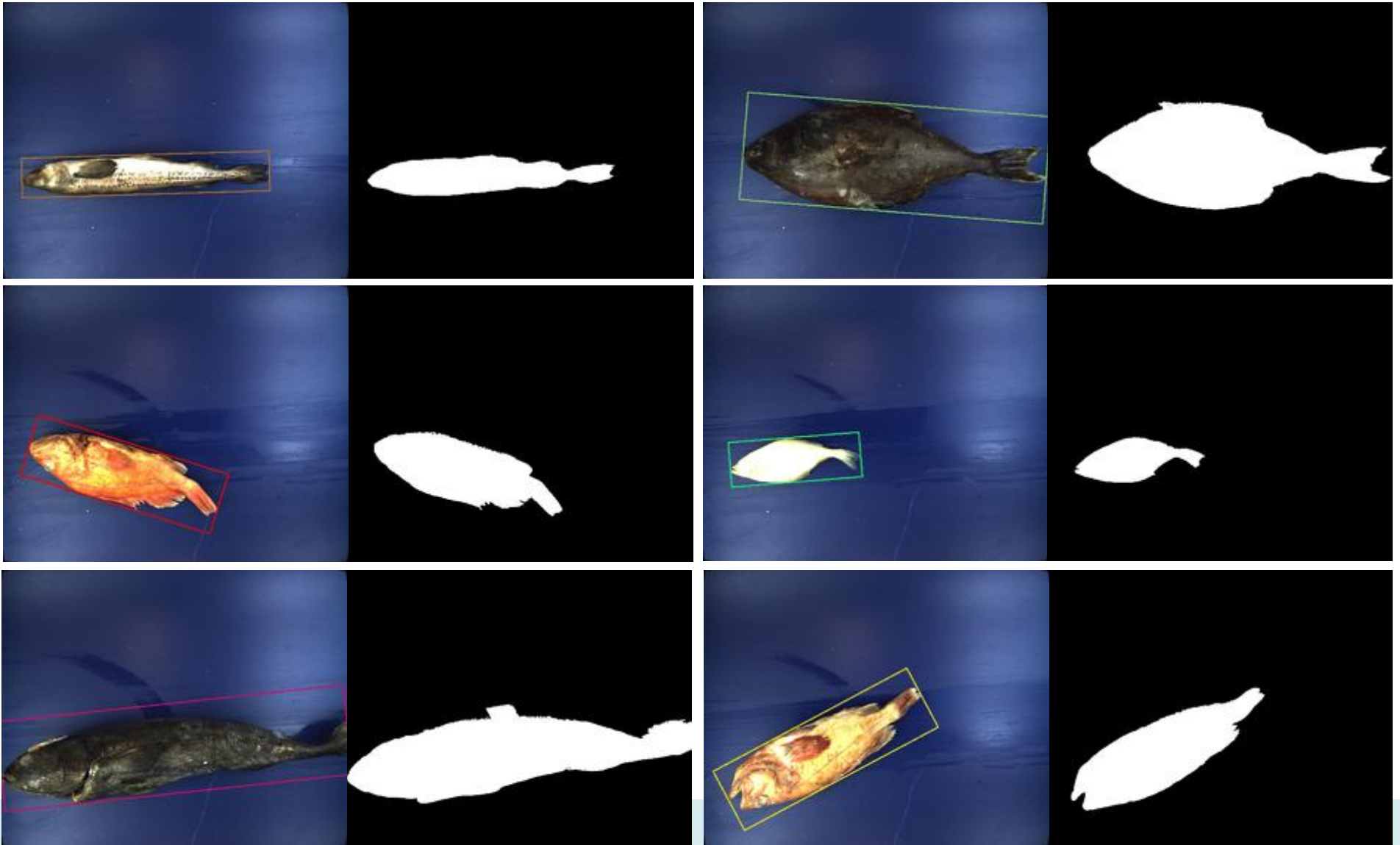
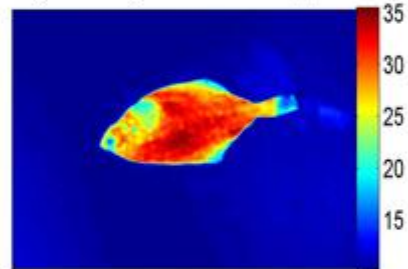


Image Processing

original fish image



background/foreground membership probability



fish extracted and length estimated



Image Processing (AFSC MACE)



Beta test version

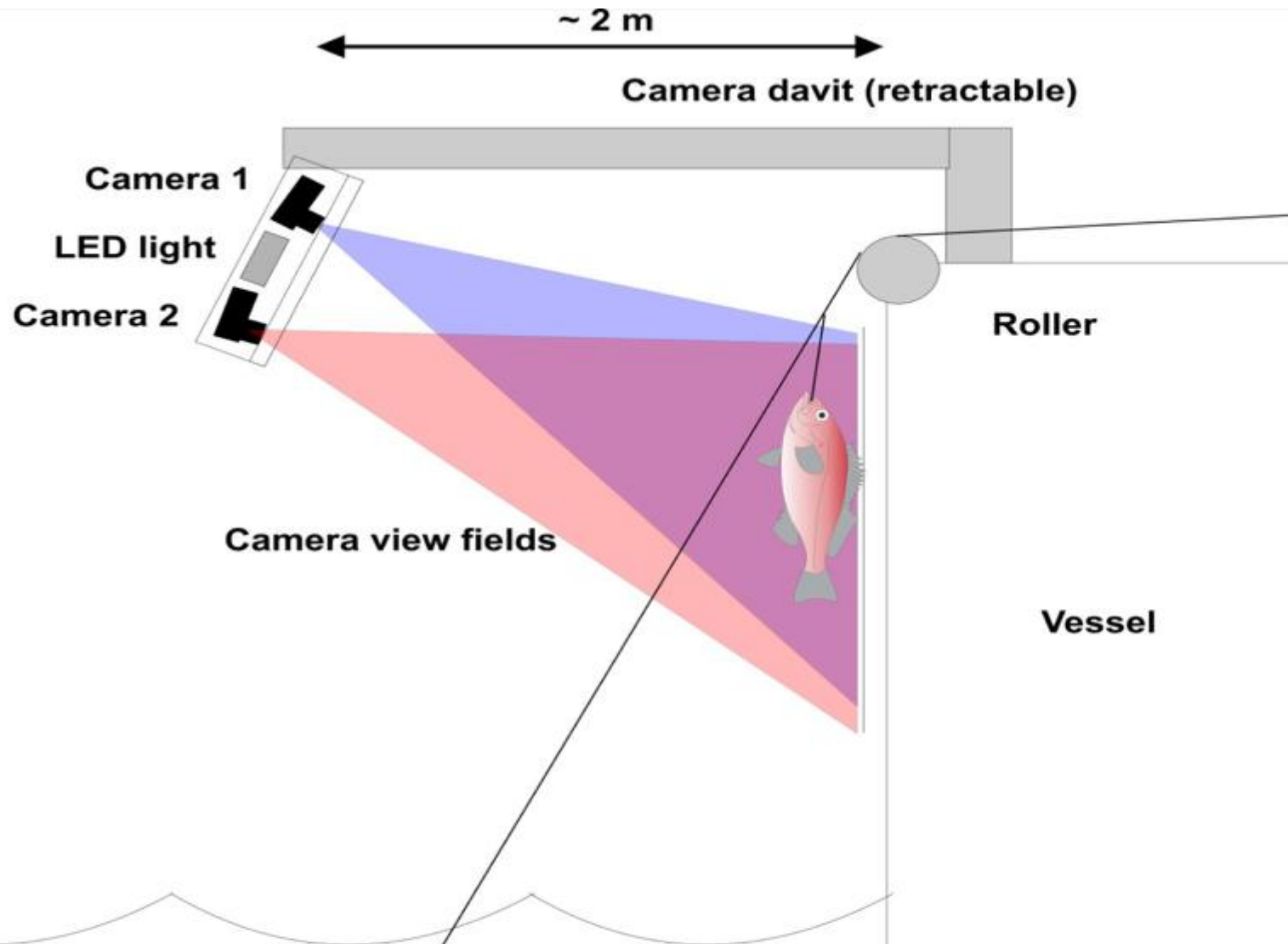
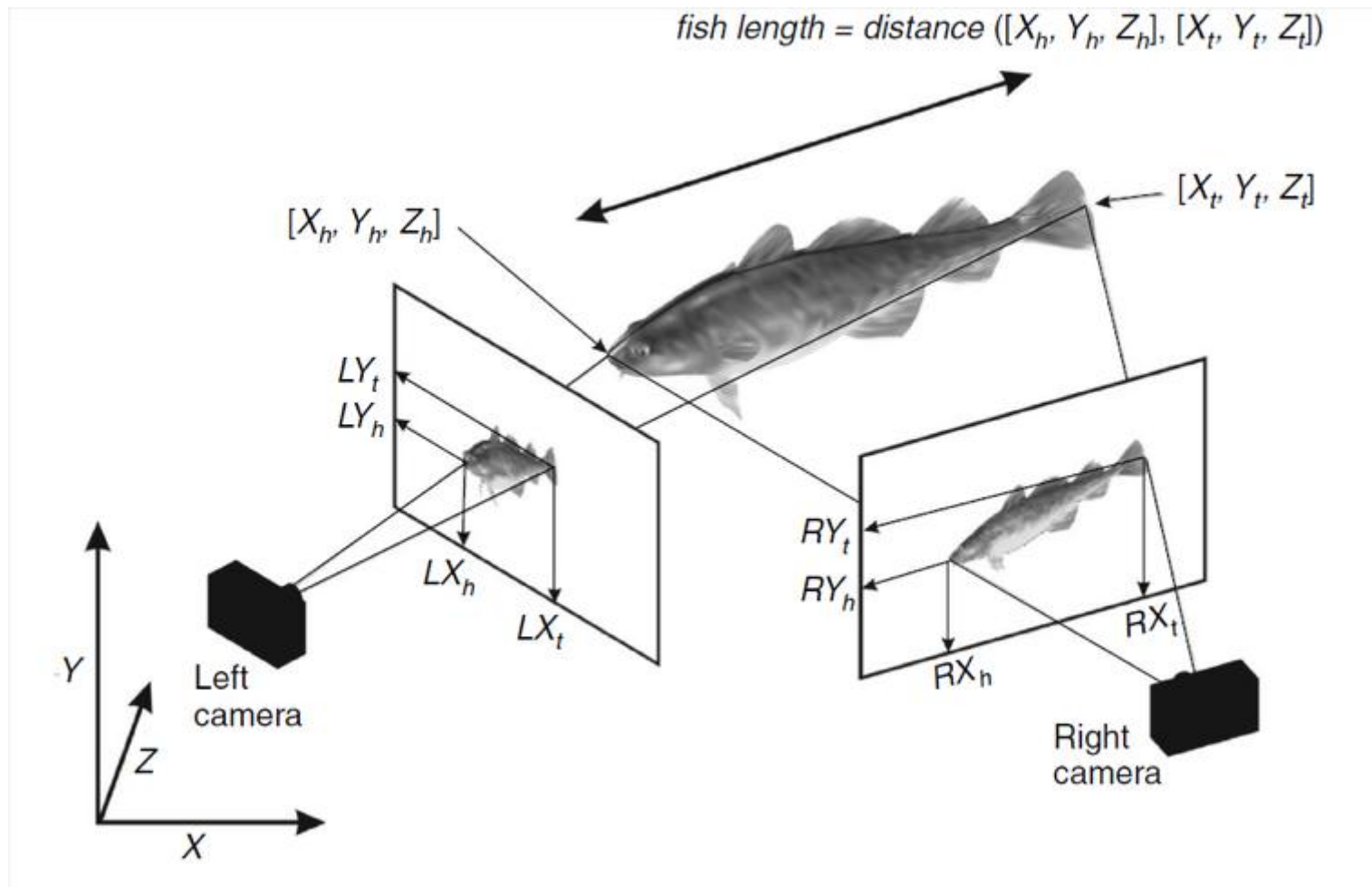


Image Processing (Williams et al. 2010)



Ongoing and Future EM Work

Non Field

- Continue hardware improvements
- Improve application for image processing
- Develop quantitative approach to species identification
 - UWEE Information Processing Lab

Ongoing and Future EM Work

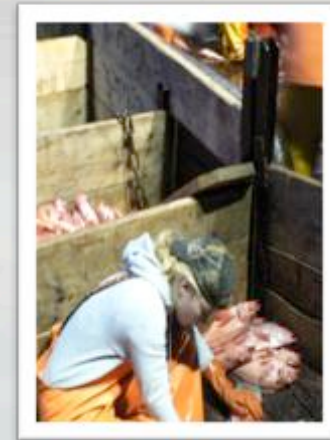
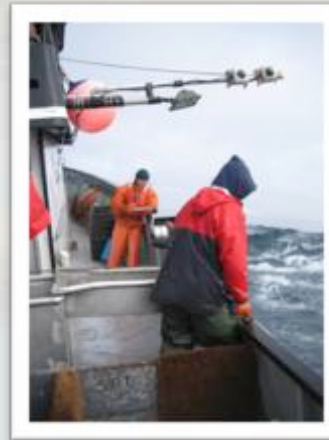
Field Studies

- Cooperative research fixed gear industry
 - Deploy camera based EM
 - Integration of Sensor data and Elogbooks
- Cooperative stereo camera research PVOA
- Camera chute system being deployed to factory trawler
- EM Workgroup



2014 Observer Program

Changes to support sustainable fisheries



Questions?